

MANIPULATORS MOBILE HANDLING STATIONS



PREVENT THE PROBLEM WITH

MOST COMMON
TYPE OF INJURIES



CUTS AND WOUNDS

SHOULDERS



R14

SPRAINS AND STRAINS



FRACTURES

MOST COMMON

HANDS



OVERWEARINESS



REPETITIVE ACTIONS



BUMP, CUT OR CAUGHT BY EQUIPMENT

BACK

KNEES

ANKLES

ERGONOMIC APPLICATIONS



ELIMINATE THE MOST COMMON CAUSES OF WORKER INJURIES



WORKER CAN BE MORE PRODUCTIVE WITH LESS STRAIN



THE WEIGHT LOAD IS TAKEN OFF THE WORKER

> WORKER SAFETY



MAINTAINING SAFETY DISTANCES FOR WORKERS LIMBS



CARRY THE TOOL IN TIGHT SPACES WHILE KEEPING WORKERS SAFE



CUTS THE LARGE COSTS OF WORKER INJURIES





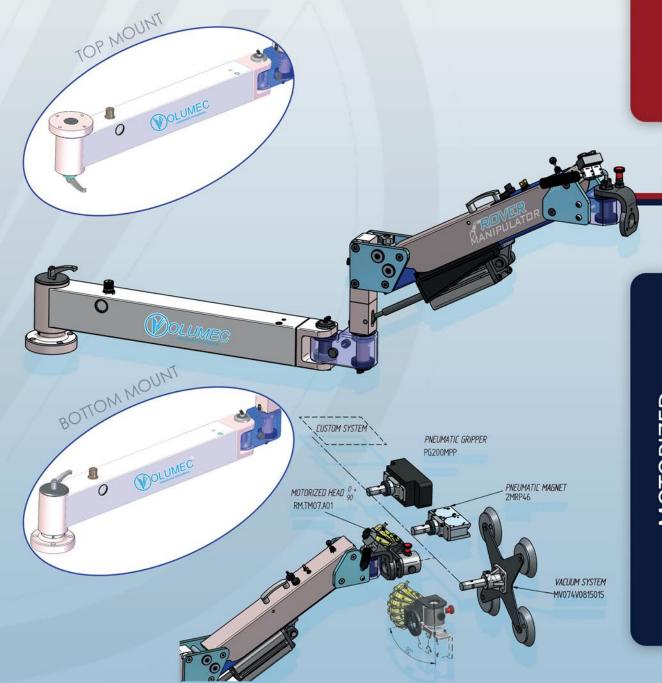


ROVER MANIPULATOR

ROVER RM01 MANIPULATORS allows you to lift, move and rotate your parts weighing from 1 to 100 kg with ease thanks to an ergonomic and easy to use system.

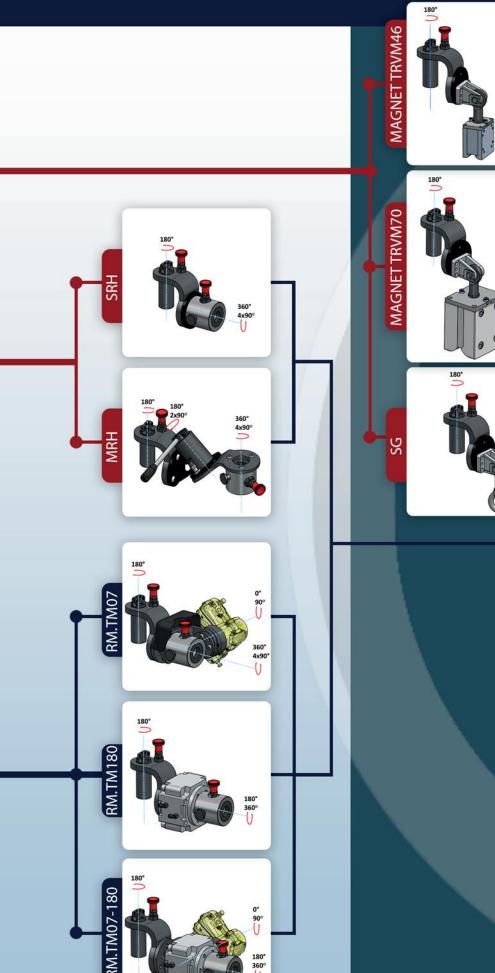
The gripping systems are interchangeable according to the type of parts to be handled and with the motorized heads it is also possible to perform rotations on one or more axes.

With the **CSM001** and **CSM002** bases, the Rover becomes a mobile manipulation station that can be quickly placed in different workstations.





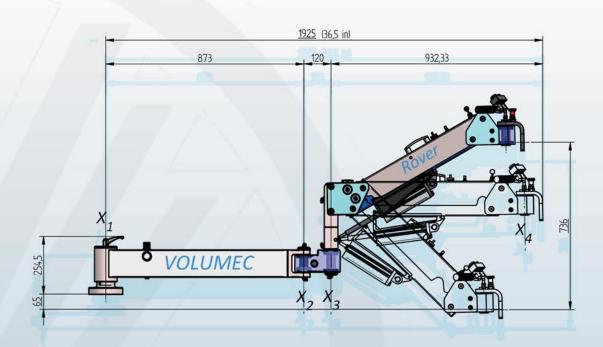
Max 170 Kg 375 lb

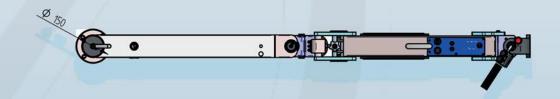






WORKING AREA







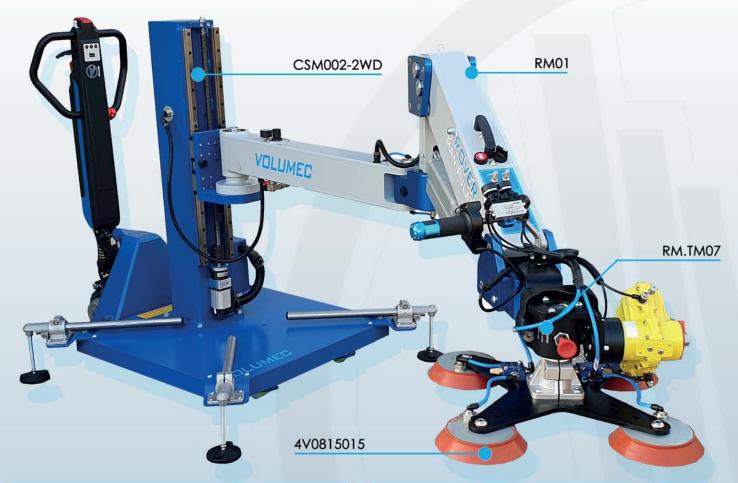
TECHNICAL DATA

LIFTING	From 1 to 100 Kg (2,2 - 220 lb)		
WORKRAY	1925mm (75,8 in) + Head		
VERTICAL STROKE	736 mm (29 in)		
GRIPPING SYSTEMS	Pneumatic Magnet, Vacuum or Pneumatic Gripper		
WEIGHT	60 Kg (130 lb)		
PRESSURE	6-8 bar		
SPEED	Outward and return		
OPERATING TEMPERATURE	10°-45° C		
ROTATION	X1=360°/ X2=180°/ X3=180°/ X4 =180°		

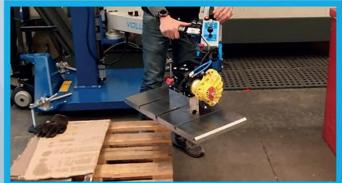


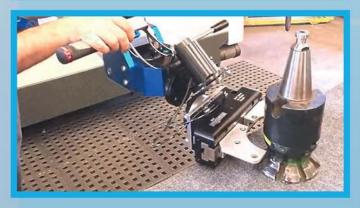
ROVER MANIPULATOR

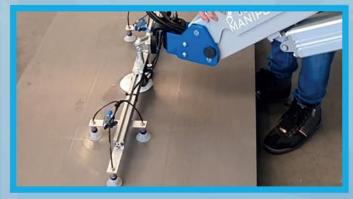
EXAMPLES AND APPLICATIONS











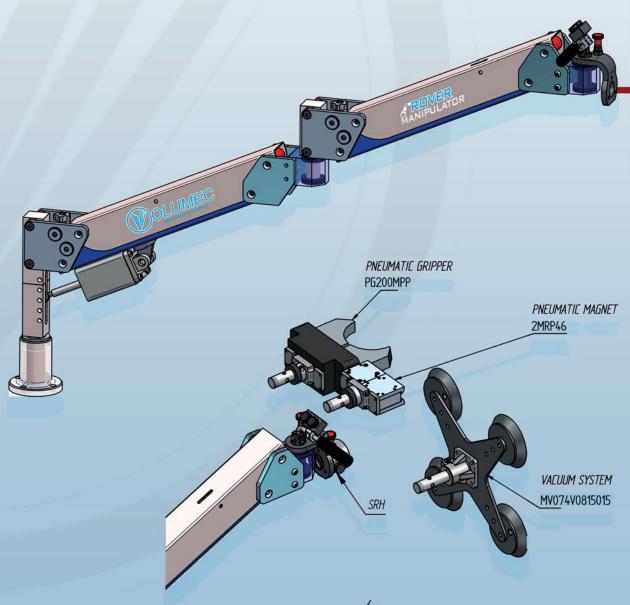


The ROVER RM02 MANIPULATORS allows you to easily lift and move your pieces weighing from 1 to 50 kg (110 lb) thanks to an ergonomic and easy-to-use system.

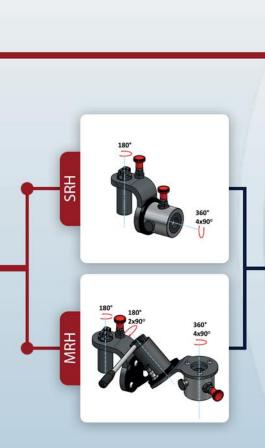
The first arm can be adjusted in height before carrying out the manipulation and then allows to use the entire vertical lifting stroke.

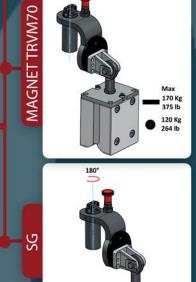
The gripping systems are interchangeable according to the type of pieces to be handled.

With the CSM001 and CSM002 bases, the Rover becomes a mobile handling station that can be quickly placed in different workstations









MAGNET TRVM46



GRIPPER 1



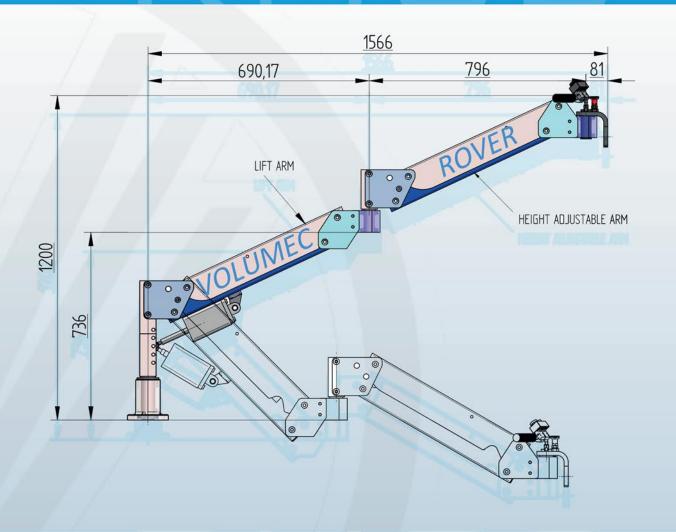








WORKING AREA



ROVER MANIPULATOR

TECHNICAL DATA

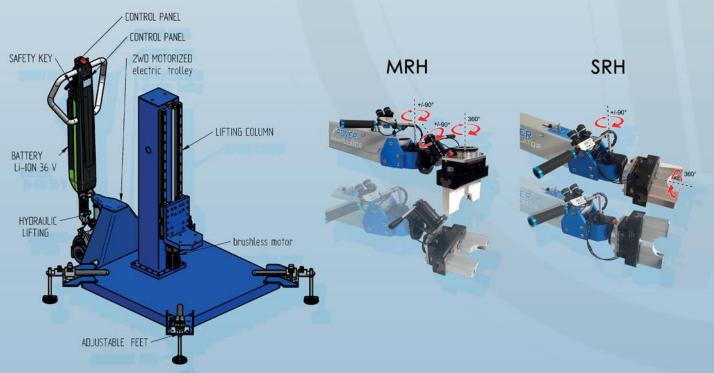
LIFTING	From 1 to 50 Kg (2,2 - 110 lb)		
WORKRAY	1685 mm (66,3 in) + HEAD		
VERTICAL STROKE	736 mm (+500 Regulation) - 29 in (+20 Regulation)		
GRIPPING SYSTEMS	Pneumatic Magnet, Vacuum or Pneumatic Gripper		
WEIGHT	40 Kg (88,2 lb)		
PRESSURE	6-8 bar		
SPEED REGULATION	Outward and return		
OPERATING TEMPERATURE	10°-45° C		
ROTATION	X1=360°/ X2=180°/ X3=180°/ X4=180°		





EXAMPLES







EASYARM MANIPULATOR

EASYARM MANIPULATOR is a pneumatic articulated arm system able to lift up until 30 Kg of weight (66 lb).

The head is equipped with the lifting control and the gripping system which can be magnetic / vacuum or hook















PLASTIC-GLASS PARTS



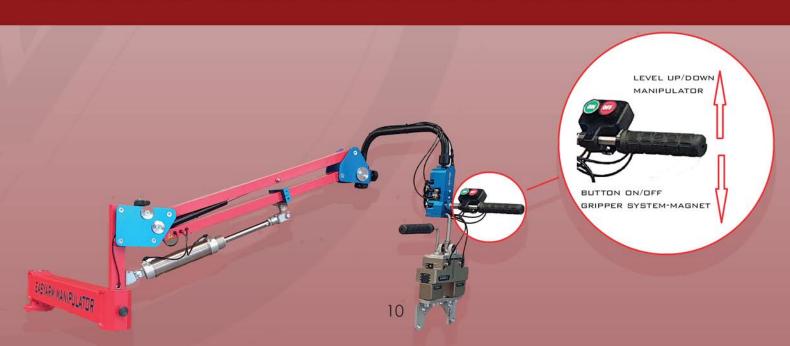
BOXES



FLAT PARTS



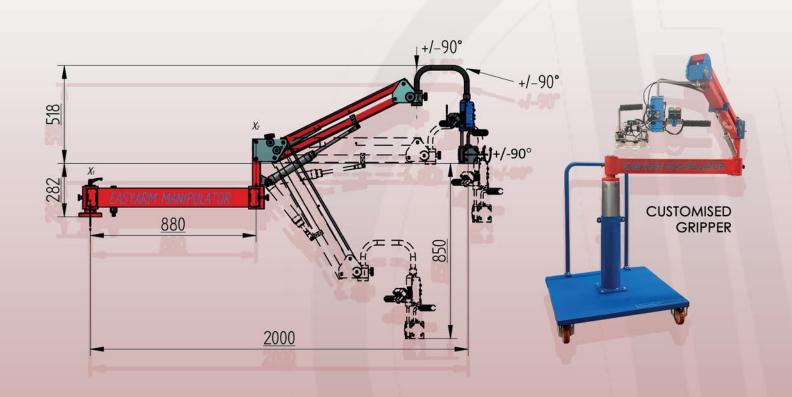
EXAMPLE: EAMO2-CUSTOM





EASYARM MANIPULATOR

WORKING AREA



EASYARM TECHNICAL DATA

CODE	EAM2-00	EAM2-01	EAM2-02	EAM2-012
GRIPPING SYSTEM	RING	VACUUM	PNEUMATIC MAGNET	PNEUMATIC MAGNET + VACUUM
PRESSURE	6-8 Bar	6-8 Bar	5-8 Bar	5-8 / 6-8 Bar
GRIPPING CAPACITY ON STEEL FLAT PIECE	1	1-25 Kg (2,2 - 55 lb)	1-46 Kg (2,2 - 101 lb)	1-46 kg (2,2 - 101 lb)
GRIPPING CAPACITY ON STEEL ROUND PIECE	1	NO	1-30 Kg (2,2 - 66 lb)	1-30 kg (2,2 - 66 lb)
PLASTIC/GLASS/BOX ALUMI- NUM/STAINLESS STEEL /ETC	1	1-25 Kg (2,2 - 55 lb)	No	No
WORKING AREA MIN-MAX	100-1950 mm (4 - 76,8 in)			
LIFTING WEIGHT	1-30 Kg (2,2 - 66 lb)	1-28 Kg (2,2 - 62 lb)	1-28 Kg (2,2 - 62 lb)	1-28 Kg (2,2 - 62 lb)



ROVER MANIPULATOR

ACCESSORIES



CSM001: BASEMENT WITH FIXED COLUMN 800X800 mm
Total height H= 500 mm.
Weight: 350 Kg (772 lb).

CSM001-2WD: TROLLEY WITH FIXED COLUMN 800X800 mm Electric motorized trolley. Total height H=500 mm. Total weight 430 kg (948 lb).



CSM002: BASEMENT FOR MANIPULATOR WITH ADJUSTABLE LIFTING COLUMN Column H= 1060 mm and stroke 600mm.

Handling through brushless motor 400W – 220 V.

Piloting by electronic accelerator and up and down buttons.

Weight: 400 Kg (882 lb)



Electric motorized trolley.

Column H= 1060 mm and stroke 600mm.

Handling through brushless motor 400W – 220 V.

Piloting by electronic accelerator and up and down buttons. Total weight 480 kg (1058 lb).



CM600/CM1000: ADJUSTABLE LIFTING COLUMN

Column H=1060/1460 mm and stroke 600/1000 mm.
Handling through brushless motor 400W – 220 V.
Arranged for floor fixing.



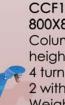


EASYARM MANIPULATOR

ACCESSORIES



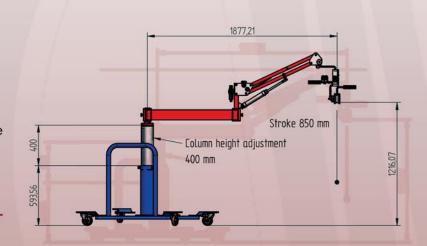
CCM001-EAM: TROLLEY WITH LIFTING COLUMN 800X800X30 mm Lifting column H=2000 mm with 4 turning wheels, 2 with brakes. Piloting by electric or pneumatic screwdriver Weight 220 Kg(485 lb).



CCF100-EAM: TROLLEY 800X800X30 mm Column with adjustable height 650mm-1050 mm. 4 turning wheels,

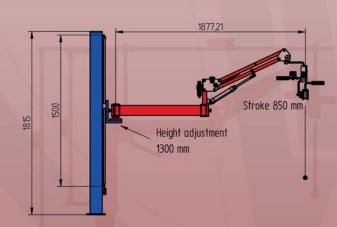
2 with brakes.

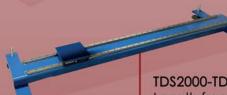
Weight: 185 Kg (408 lb).





CCF001: LIFTING COLUMN h=1850 mm Piloting by electric or pneumatic screwdriver. Weight 60 kg (132 lb).





TDS2000-TDS4000: FLOOR RAIL Length from 2000 to 4000 mm with manual movement

(motorized optional).



VOLUMEC MANIPULATOR DATA COLLECTION CARD

NAME AND SURNAME				
COMPANY				
ADDRESS				
REFERENT E-MAIL ADDRESS				<u> </u>
PHONE	-			
WEIGHT TO LIFT:	TYPE OF MA	TERIAL TO HAND	DLE:	
☐ 1-30 KG	☐ Magnetical	☐ Magnetically conductive ferrous material ☐ Aluminium		
☐ 1-100 KG	☐ Plastic	☐ Glass	Stainless steel	Cardboard
	Other:specif	ły		
PIECE SHAPE:				
☐ Plane	(Indicate dime	nsions: x=	., y=, z=)
Cylindrical		nsions: Ø= île, internal diametei	, thickness=)	
Other:specify				Release point
H. minmm	h. mgx	Pick	up point	mm
	H. max	ANGLES	DOTATION NEEDED.	-
GRIPPING POSITION:	P GRIPPING	200 A PARAMETER (100 MARCH 1200 - 2	OTATION NEEDED:	250
FRONT D	RIPPING	Revolvin	g head 0-90°	90'
DESCRIPTION OF HANDLIN	G OPERATIONS:		head 0-180°	The second second
		Revolvin Rotating	g 0-90° + 0-180° head	



NOTES





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