





MANIPULATORS MOBILE HANDLING STATIONS



PREVENT THE PROBLEM WITH

MOST COMMON
TYPE OF INJURIES



CUTS AND

SHOULDERS



ELIMINATE THE MOST COMMON CAUSES OF WORKER INJURIES

ERGONOMIC APPLICATIONS



WORKER CAN BE MORE PRODUCTIVE WITH LESS STRAIN



FRACTURES

SPRAINS AND

STRAINS

BACK

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THE WEIGHT LOAD IS TAKEN OFF THE WORKER

CAUSES OF INJURIES

HANDS



MAINTAINING SAFETY DISTANCES FOR WORKERS LIMBS

WORKER

SAFETY



OVERWEARINESS





CARRY THE TOOL IN TIGHT SPACES WHILE KEEPING WORKERS SAFE



REPETITIVE

ANKLES



BUMP, CUT OR CAUGHT BY EQUIPMENT



CUTS THE LARGE COSTS OF WORKER INJURIES





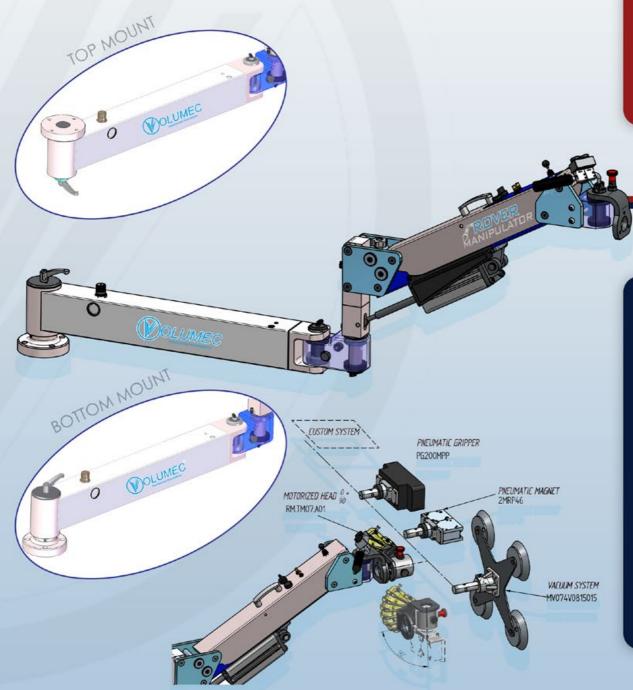




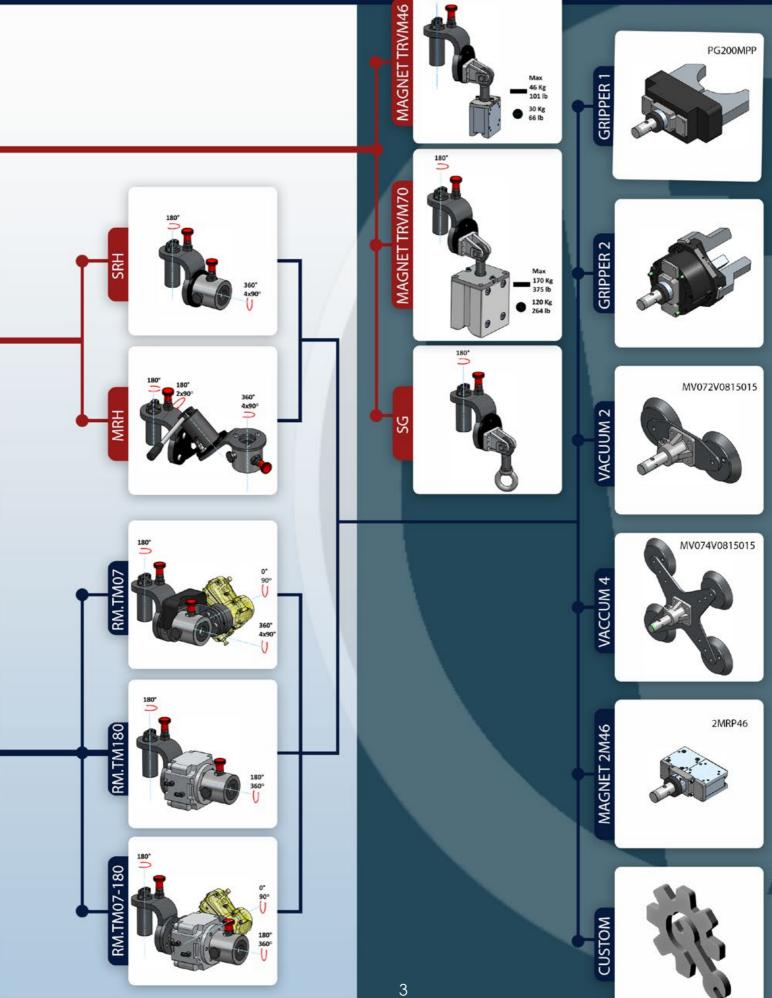
ROVER RM01 MANIPULATORS allows you to lift, move and rotate your parts weighing from 1 to 100 kg with ease thanks to an ergonomic and easy to use system.

The gripping systems are interchangeable according to the type of parts to be handled and with the motorized heads it is also possible to perform rotations on one or more axes.

With the **CSM001** and **CSM002** bases, the Rover becomes a mobile manipulation station that can be quickly placed in different workstations.



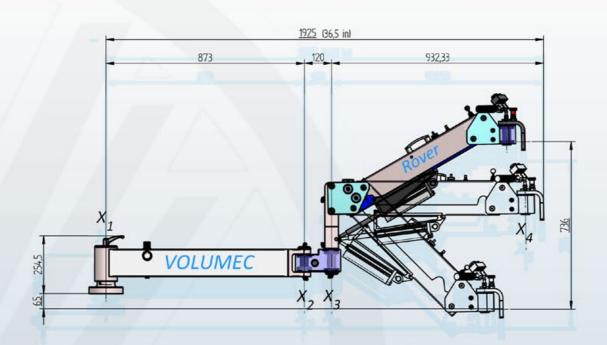


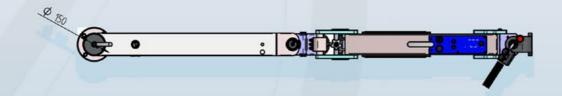






WORKING AREA







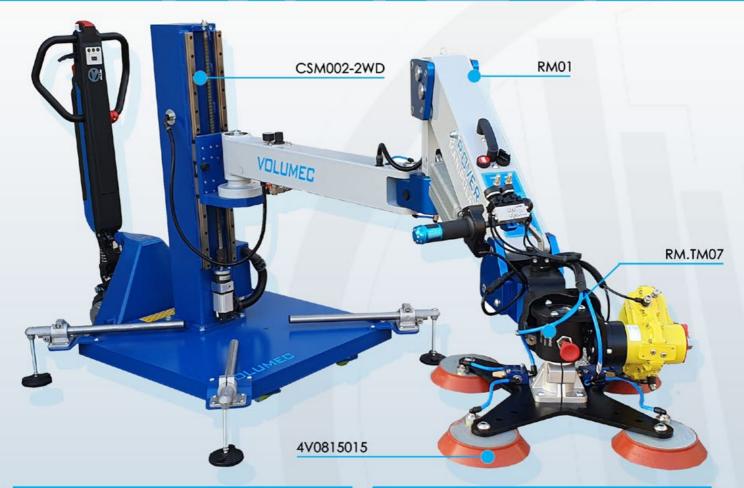
TECHNICAL DATA

LIFTING	From 1 to 100 Kg (2,2 - 220 lb)
WORKRAY	1925mm (75,8 in) + Head
VERTICAL STROKE	736 mm (29 in)
GRIPPING SYSTEMS	Pneumatic Magnet, Vacuum or Pneumatic Gripper
WEIGHT	60 Kg (130 lb)
PRESSURE	6-8 bar
SPEED	Outward and return
OPERATING TEMPERATURE	10°-45° C
ROTATION	X1=360°/ X2=180°/ X3=180°/ X4 =180°



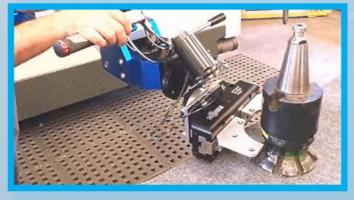
ROVER MANIPULATOR

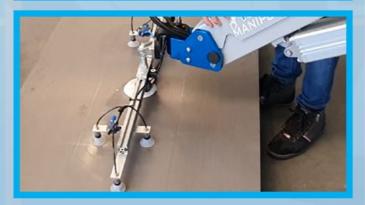
EXAMPLES AND APPLICATIONS













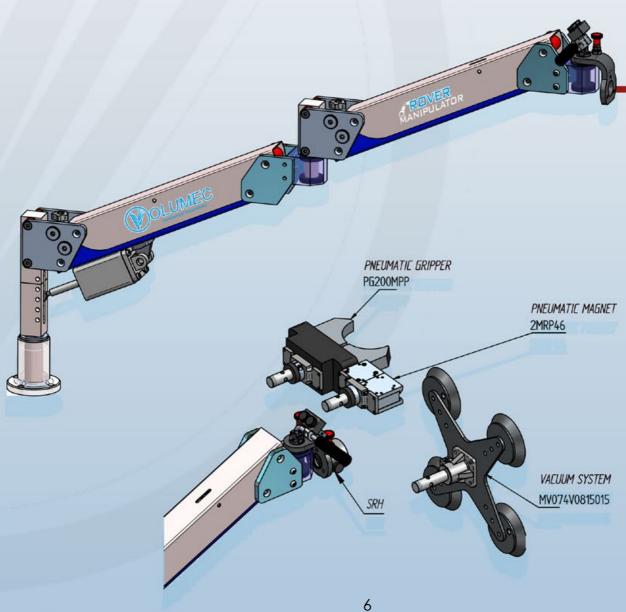


The ROVER RM02 MANIPULATORS allows you to easily lift and move your pieces weighing from 1 to 50 kg (110 lb) thanks to an ergonomic and easy-to-use system.

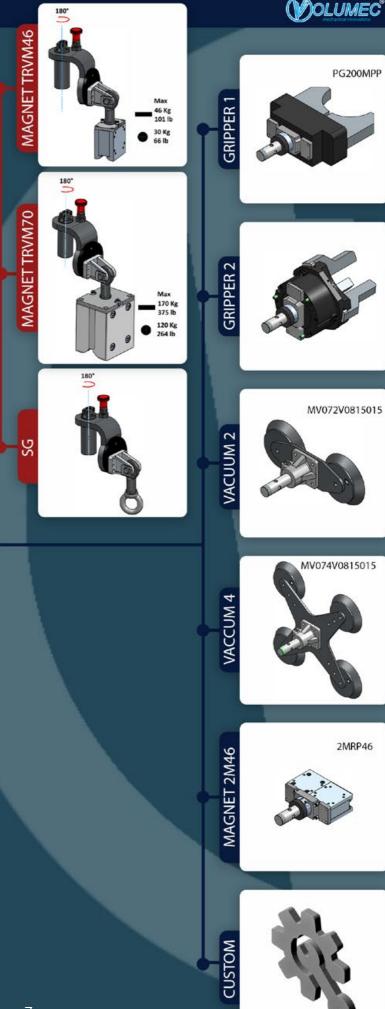
The first arm can be adjusted in height before carrying out the manipulation and then allows to use the entire vertical lifting stroke.

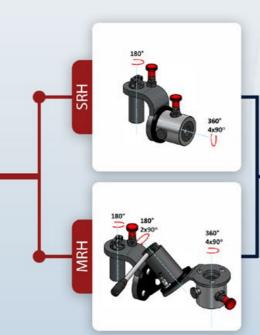
The gripping systems are interchangeable according to the type of pieces to be handled.

With the CSM001 and CSM002 bases, the Rover becomes a mobile handling station that can be quickly placed in different workstations





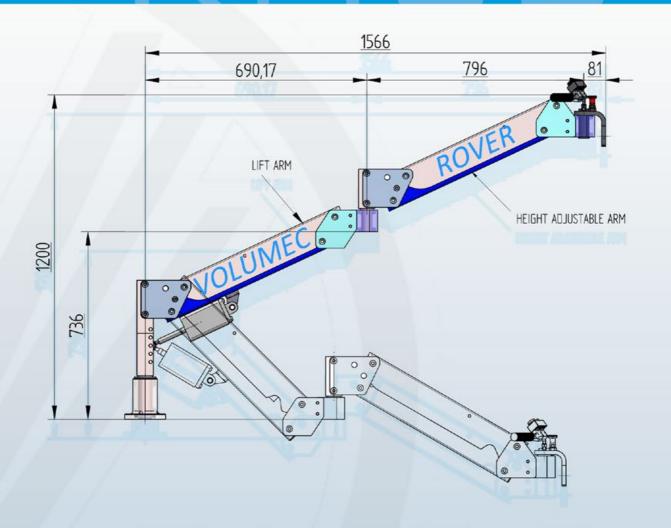








WORKING AREA





TECHNICAL DATA

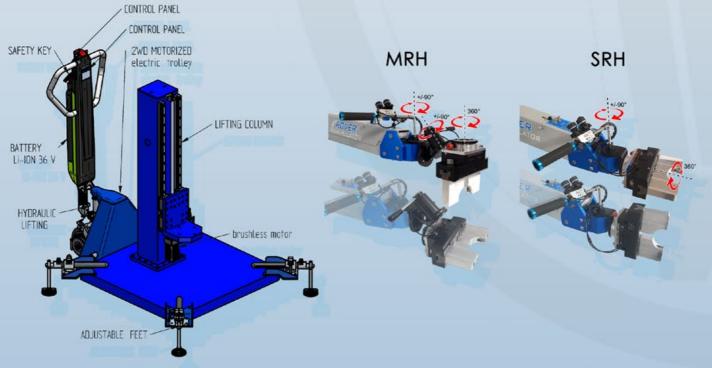
LIFTING	From 1 to 50 Kg (2,2 - 110 lb)	
WORKRAY	1685 mm (66,3 in) + HEAD	
VERTICAL STROKE	736 mm (+500 Regulation) - 29 in (+20 Regulation)	
GRIPPING SYSTEMS	Pneumatic Magnet, Vacuum or Pneumatic Gripper	
WEIGHT	40 Kg (88,2 lb)	
PRESSURE	6-8 bar	
SPEED REGULATION	Outward and return	
OPERATING TEMPERATURE	10°-45° C	
ROTATION	X1=360°/ X2=180°/ X3=180°/ X4 =180°	





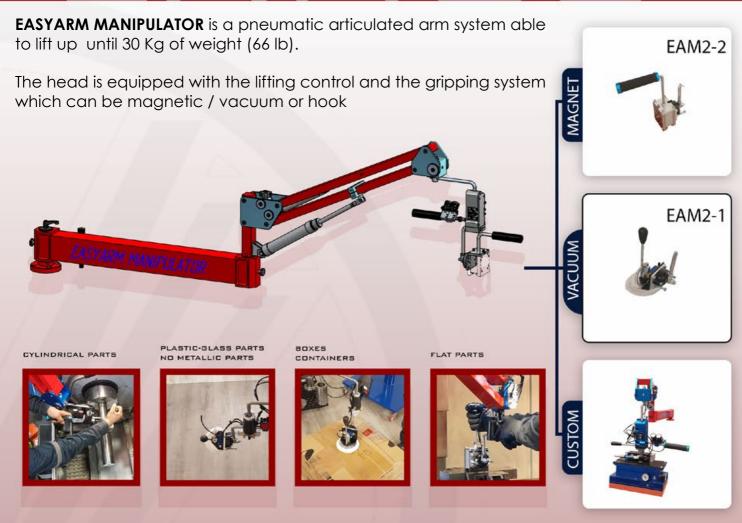
EXAMPLES







EASYARM MANIPULATOR



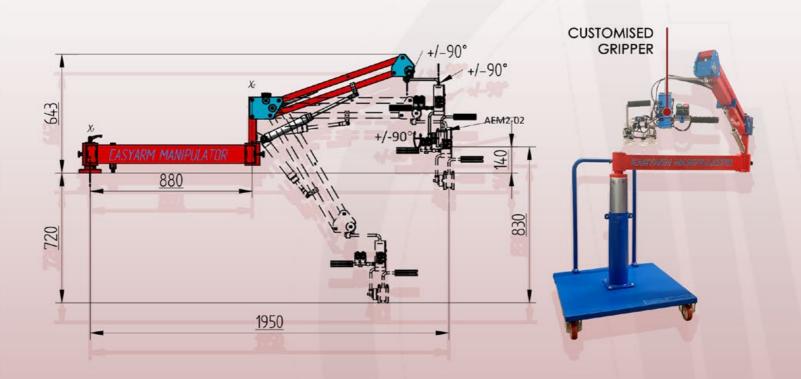
EXAMPLE: EAMO2-01





EASYARM MANIPULATOR

WORKING AREA



EASYARM TECHNICAL DATA MANIPULATOR TECHNICAL DATA

CODE	EAM2-00	EAM2-01	EAM2-02	EAM2-012
EASYARM MANIPULATOR WITH	Only Head	VACUUM	pneu. magnet	magnet + vacuum
PRESSURE	6-8 Bar	6-8 Bar	5-8 Bar	5-8 / 6-8 Bar
GRIPPING CAPACITY ON STEEL FLAT PIECE	/	1-25 Kg (2,2 - 55 lb)	1-46 Kg (2,2 - 101 lb)	1-46 kg (2,2 - 101 lb)
GRIPPING CAPACITY ON STEEL ROUND PIECE	/	NO	1-30 Kg (2,2 - 66 lb)	1-30 kg (2,2 - 66 lb)
PLASTIC/GLASS/BOX ALUMI- NUM/STAINLESS STEEL /ETC	/	1-25 Kg (2,2 - 55 lb)	No	No
WORKING AREA MIN-MAX	100-1950 mm (4 - 76,8 in)			
BALANCED ARM	1-30 Kg (2,2 - 66 lb)	1-28 Kg (2,2 - 62 lb)	1-28 Kg (2,2 - 62 lb)	1-28 Kg (2,2 - 62 lb)



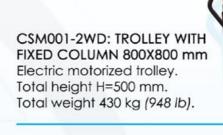


ACCESSORIES



CSM001: BASEMENT WITH FIXED COLUMN 800X800 mm

Total height H= 500 mm. Weight: 350 Kg (772 lb).





CSM002: BASEMENT FOR MANIPULATOR WITH ADJUSTABLE LIFTING COLUMN Column H= 1060 mm and stroke 600mm.

Handling through brushless motor 400W – 220 V.

Piloting by electronic accelerator and up and down buttons.

Weight: 400 Kg (882 lb)



Column H= 1060 mm and stroke 600mm.

Handling through brushless motor 400W – 220 V.

Piloting by electronic accelerator and up and down buttons. Total weight 480 kg (1058 lb).



CM600/CM1000: ADJUSTABLE LIFTING COLUMN

Column H=1060/1460 mm and stroke 600/1000 mm.
Handling through brushless motor 400W – 220 V.
Arranged for floor fixing.

TDS2000-TDS4000: FLOOR RAIL Length from 2000 to 4000 mm with manual movement (motorized optional).



EASYARM MANIPULATOR

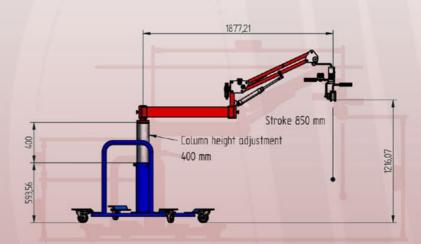
ACCESSORIES



CCM001: TROLLEY WITH LIFTING COLUMN 800X800x30 mm with 4 turning wheels, 2 with brakes, lifting column h=2000mm. Piloting by electric or pneumatic screwdriver. Weight: 220 Kg (485 lb).

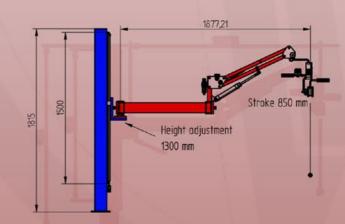


CCF100-EAM: TROLLEY 800X800X30 mm
Column with adjustable height 650mm-1050 mm.
4 turning wheels,
2 with brakes.
Weight: 185 Kg (408 lb).





CCF001: LIFTING COLUMN h=1850 mm
Piloting by electric or pneumatic screwdriver.
Weight 60 kg (132 lb).



TDS2000-TDS4000 Length from 2000

TDS2000-TDS4000: FLOOR RAIL Length from 2000 to 4000 mm with manual movement (motorized optional).



VOLUMEC MANIPULATOR DATA COLLECTION CARD

NAME AND SURNAME					
COMPANY	7 / \				
ADDRESS				_	
REFERENT E-MAIL ADDRESS			\ \footnote{\chi_1}		
PHONE					
WEIGHT TO LIFT:	TYPE OF MAT	TYPE OF MATERIAL TO HANDLE:			
☐ 1-30 KG	☐ Magnetically	y conductive ferrous	material	Aluminium	
☐ 1-100 KG	☐ Plastic	Glass	Stainless steel	Cardboard	
	Other:specif	y			
PIECE SHAPE:					
☐ Plane	(Indicate dimen	sions: x=	, y=, z=)	
Cylindrical		sions: Ø=le, internal diameter	., thickness=) : Ø=))	
Other:specify				Release point	
VERTICAL STROKE REQUEST H. minmm H. maxmm	TED:	Pick	up point X =	mm	
GRIPPING POSITION:	 	ANGLES I	ROTATION NEEDED:	20	
	P GRIPPING	☐ No rotati	on (only 1 rotation manu	al)	
FRONT (GRIPPING	☐ Revolvin	g head 0-90°	507	
DESCRIPTION OF HANDLIN	G OPERATIONS:	☐ Rotating	head 0-180°		
		Revolvin Rotating	g 0-90° + 0-180° head		



NOTES





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